

High Probability

Definition 18 (High Probability)

We say a **randomized** algorithm has running time $\mathcal{O}(\log n)$ with **high probability** if for any constant α the running time is at most $\mathcal{O}(\log n)$ with probability at least $1 - \frac{1}{n^\alpha}$.

Here the \mathcal{O} -notation hides a constant that may depend on α .

$g(n)$

Probability

for any constant α

$$f(\alpha, n) = \Theta(g(n))$$

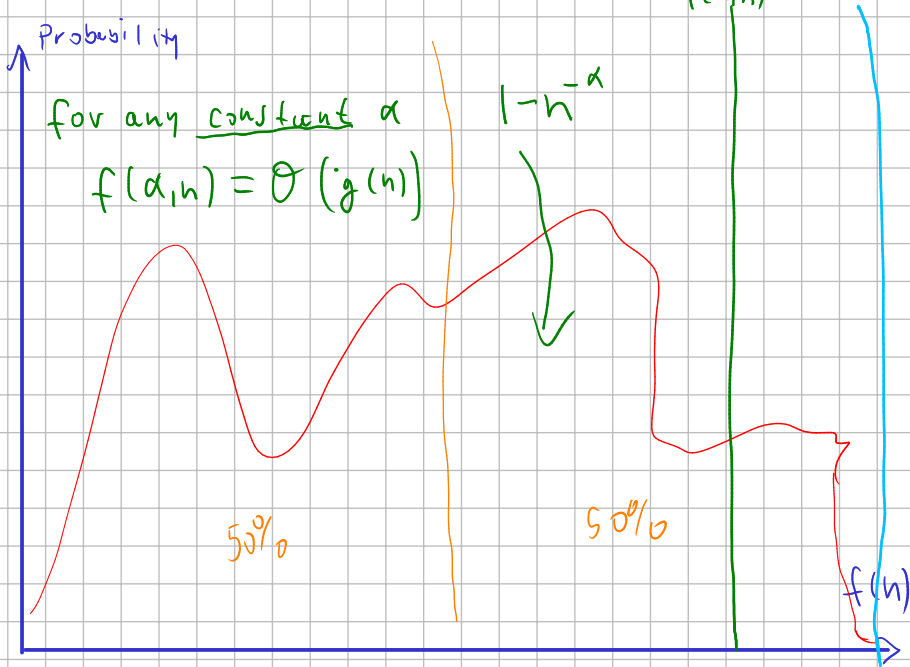
$$1 - n^{-\alpha}$$

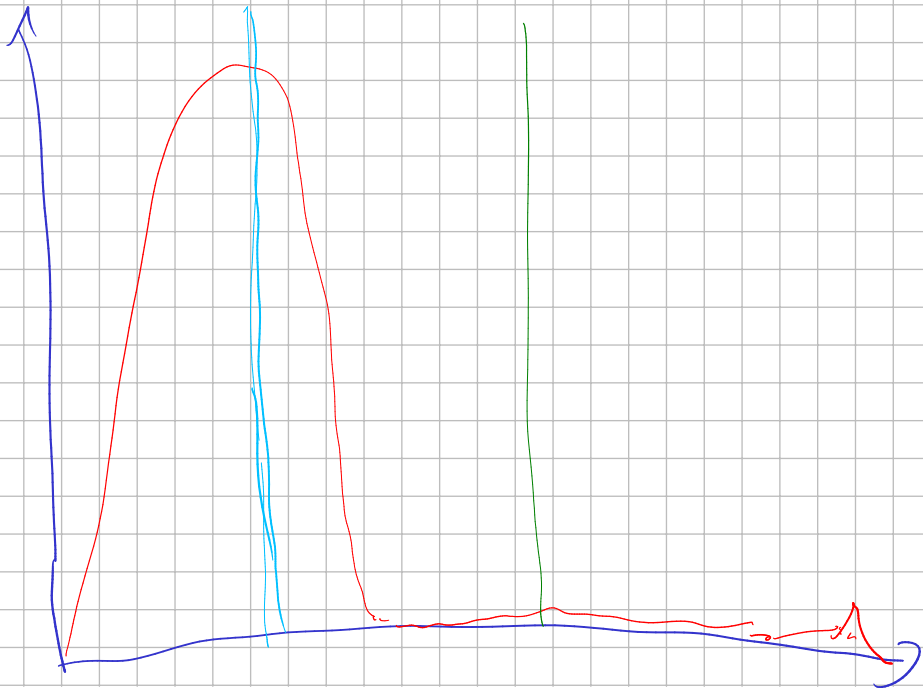
$f(\alpha, n)$

50%

50%

$f(n)$





High Probability

Suppose there are **polynomially** many events E_1, E_2, \dots, E_ℓ , $\ell = n^c$ each holding with high probability (e.g. E_i may be the event that the i -th search in a skip list takes time at most $\mathcal{O}(\log n)$).

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$$\Pr[E_1 \wedge \dots \wedge E_\ell]$$

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$$f(\alpha', n) = \mathcal{O}(\log n)$$

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$$\begin{aligned} \Pr[E_1 \wedge \dots \wedge E_\ell] &= 1 - \Pr[\bar{E}_1 \vee \dots \vee \bar{E}_\ell] \\ &\geq 1 - \underbrace{(n^c)}_{\text{given } \alpha} \cdot n^{-\alpha'} \\ &= 1 - n^{c-\alpha'} \\ &= 1 - n^{-\alpha} \end{aligned}$$

$\alpha' := \alpha + c$

This means $\Pr[E_1 \wedge \dots \wedge E_\ell]$ holds with high probability.

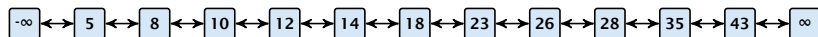
7.5 Skip Lists

Lemma 19

A search (and, hence, also insert and delete) in a skip list with n elements takes time $\mathcal{O}(\log n)$ with high probability (w. h. p.).

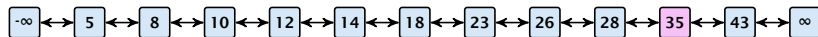
7.5 Skip Lists

Backward analysis:



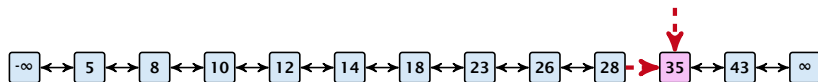
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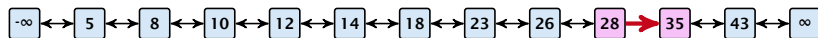
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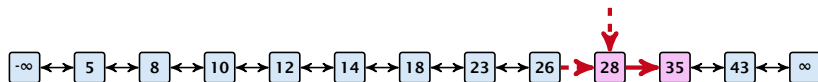
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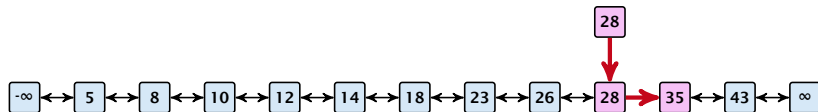
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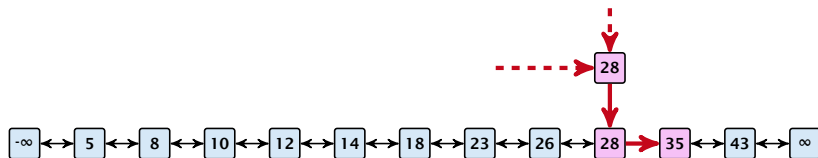
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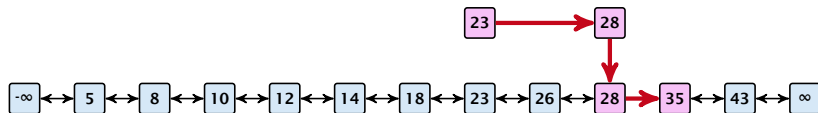
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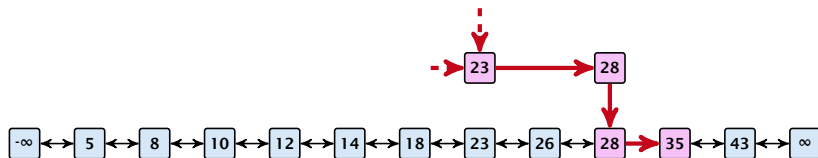
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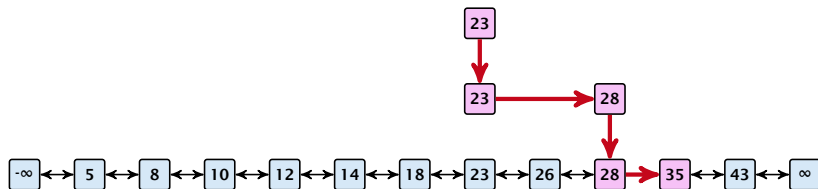
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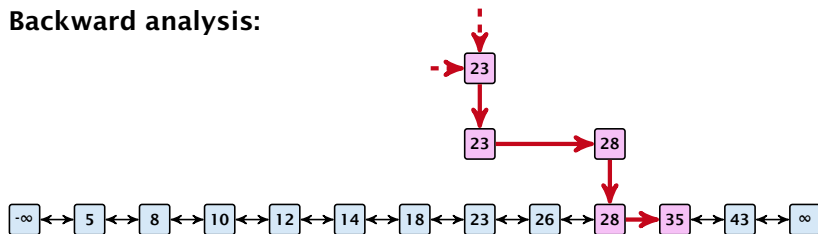
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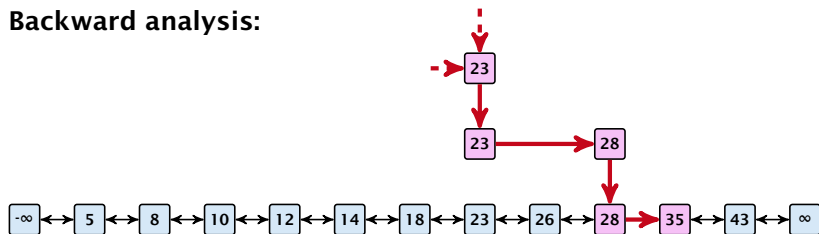
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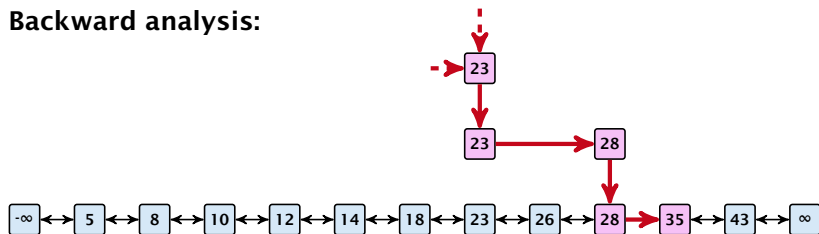
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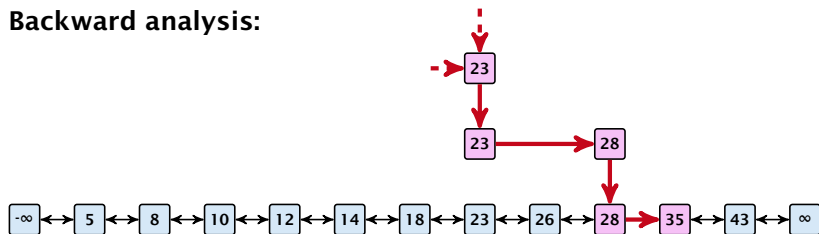
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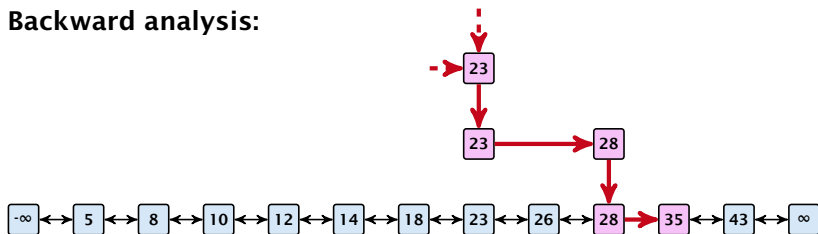
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We show that w.h.p:

- ▶ A “long” search path must also go very high.
- ▶ There are no elements in high lists.

From this it follows that w.h.p. there are no long paths.

7.5 Skip Lists

Estimation for Binomial Coefficients

$$\left(\frac{n}{k}\right)^k \leq \binom{n}{k} \leq \left(\frac{en}{k}\right)^k$$

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$$\left(\frac{n}{k}\right)^k \leq \frac{n}{k} \cdot \underbrace{\frac{n-1}{k+1} \cdot \frac{n-2}{k+2} \dots \frac{n-k+1}{k+1}}_{\leq \frac{n}{k}}$$

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$$= \left(\frac{n}{k}\right)^k \cdot \frac{k^k}{k!} \leq \left(\frac{n}{k}\right)^k \cdot \sum_{i \geq 0} \frac{k^i}{i!}$$

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In particular, this means that during the construction in the backward analysis we see at most k heads (i.e., coin flips that tell you to go up) in z trials.

7.5 Skip Lists

$$\Pr[E_{z,k}]$$

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~~A~~
 $\Pr[E_{z,k}] \leq \Pr[\text{at most } k \text{ heads in } z \text{ trials}]$

$$\leq \binom{z}{k} 2^{-(z-k)} \leq \Pr\left[\bigvee_{\vec{m}} E_{\vec{m}}\right] \leq \sum_m \Pr[E_{\vec{m}}]$$

1 2 3 4 5 - - - - - z

↑
mark $z-k$ positions

$\Pr[\text{only see tail in marked pos}] = 2^{-(z-k)}$

\vec{m} is marking

$E_{\vec{m}}$: event only tail in marked pos of \vec{m}

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$$\leq n \cdot 2^{-k} \leq n \cdot n^{-\gamma}$$

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Hence,

$$\Pr[\text{search requires } z \text{ steps}]$$

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7.5 Skip Lists

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This means, the search requires at most ~~z~~ $O(\log n)$ steps, w. h. p.

$$n^{-\alpha} + n^{1-\beta}$$

$$\leq \max\{2n^{-\alpha}, 2n^{1-\beta}\}$$

$$2n^{-\alpha} \leq n^{-\delta}$$

$$\alpha = \delta + 1$$

$$\beta = \delta + 2$$

$$n^{-\delta} \quad (10^6)^{-\delta}$$

7.6 Hashing

Dictionary:

- ▶ **$S.insert(x)$** : Insert an element x .
- ▶ **$S.delete(x)$** : Delete the element pointed to by x .
- ▶ **$S.search(k)$** : Return a pointer to an element e with $key[e] = k$ in S if it exists; otherwise return **null**.

So far we have implemented the search for a key by carefully choosing split-elements.

Then the memory location of an object x with key k is determined by successively comparing k to split-elements.

Hashing tries to **directly** compute the memory location from the given key. The goal is to have constant search time.

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Definitions:

- ▶ Universe U of keys, e.g., $U \subseteq \mathbb{N}_0$. U very large.
- ▶ Set $S \subseteq U$ of keys, $|S| = m \leq |U|$.
- ▶ Array $T[0, \dots, n-1]$ hash-table.
- ▶ Hash function $h : U \rightarrow [0, \dots, n-1]$.

The hash-function h should fulfill:

- ▶ Fast to evaluate.
- ▶ Small storage requirement.
- ▶ Good distribution of elements over the whole table.

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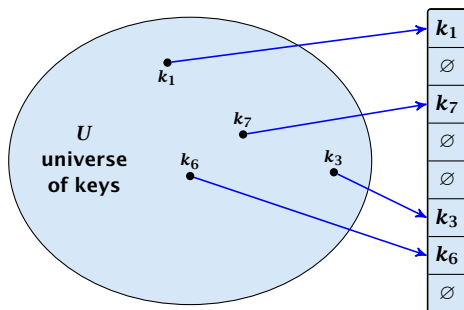
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Direct Addressing

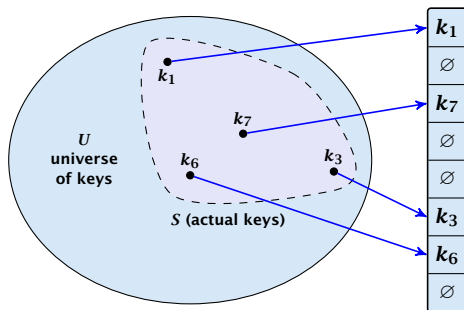
Ideally the hash function maps **all** keys to different memory locations.



This special case is known as **Direct Addressing**. It is usually very unrealistic as the universe of keys typically is quite large, and in particular larger than the available memory.

Perfect Hashing

Suppose that we **know** the set S of actual keys (no insert/no delete). Then we may want to design a **simple** hash-function that maps all these keys to different memory locations.



Such a hash function h is called a **perfect hash function** for set S .

Collisions

If we do not know the keys in advance, the best we can hope for is that the hash function distributes keys evenly across the table.

Problem: Collisions

Usually the universe U is much larger than the table-size n .

Hence, there may be two elements k_1, k_2 from the set S that map to the same memory location (i.e., $h(k_1) = h(k_2)$). This is called a **collision**.

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Typically, collisions do not appear once the size of the set S of actual keys gets close to n , but already when $|S| \geq \omega(\sqrt{n})$.

Lemma 20

The probability of having a collision when hashing m elements into a table of size n under uniform hashing is at least

$$1 - e^{-\frac{m(m-1)}{2n}} \approx 1 - e^{-\frac{m^2}{2n}}.$$

Uniform hashing:

Choose a hash function uniformly at random from all functions $f: U \rightarrow [0, \dots, n-1]$.

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$h^{|U|}$

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$$| \frac{n - (\ell - 1)}{n} |$$

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Here the first equality follows since the ℓ -th element that is hashed has a probability of $\frac{n-\ell+1}{n}$ to not generate a collision under the condition that the previous elements did not induce collisions. □