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Definition 3

An optimization problem $P = (\mathcal{I}, \text{sol}, m, \text{goal})$ is in **NPO** if

- ▶ $x \in \mathcal{I}$ can be **decided** in polynomial time
- ▶ $y \in \text{sol}(\mathcal{I})$ can be **verified** in polynomial time
- ▶ m can be computed in polynomial time
- ▶ $\text{goal} \in \{\text{min}, \text{max}\}$

In other words: the decision problem **is there a solution y with $m(x, y)$ at most/at least z** is in NP.

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- ▶ y is candidate solution
- ▶ $m^*(x)$ cost/profit of an optimal solution

Definition 4 (Performance Ratio)

$$R(x, y) := \max \left\{ \frac{m(x, y)}{m^*(x)}, \frac{m^*(x)}{m(x, y)} \right\}$$

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An algorithm A is an r -approximation algorithm iff

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Definition 6 (PTAS)

A PTAS for a problem P from NPO is an algorithm that takes as input $x \in \mathcal{I}$ and $\epsilon > 0$ and produces a solution y for x with

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Definition 8 (APX – approximable)

A problem P from NPO is in APX if there exist a constant $r \geq 1$ and an r -approximation algorithm for P .

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- ▶ Set Cover
- ▶ Minimum Multicut
- ▶ Sparsest Cut
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There are really difficult problems!

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Asymmetric k -Center admits an $\mathcal{O}(\log^* n)$ -approximation.

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Class APX not important in practise.

Instead of saying **problem P is in APX** one says **problem P admits a 4-approximation**.

One only says that a problem is **APX-hard**.

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