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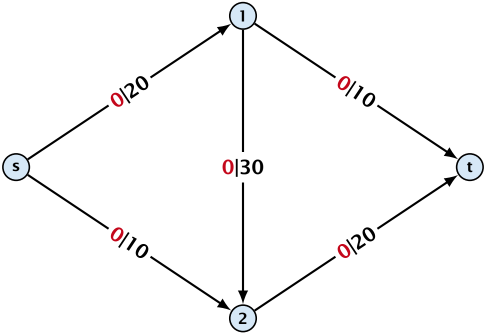

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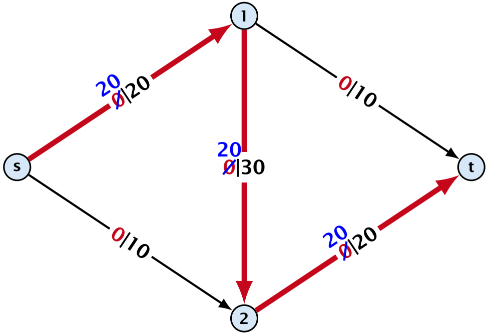

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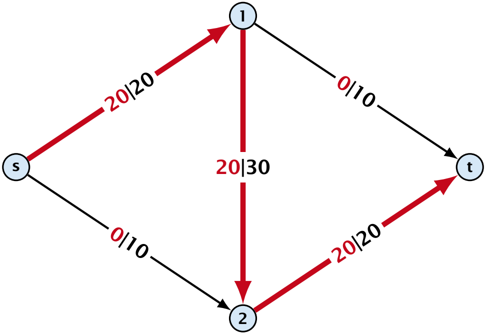

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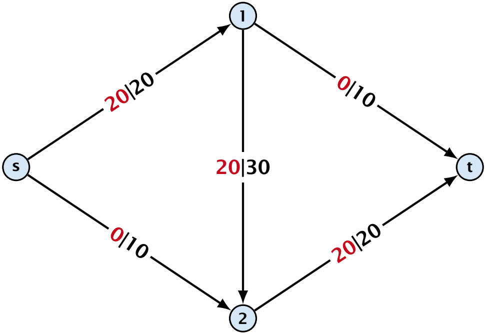

The Residual Graph

From the graph $G = (V, E, c)$ and the current flow f we construct an auxiliary graph $G_f = (V, E_f, c_f)$ (the residual graph):

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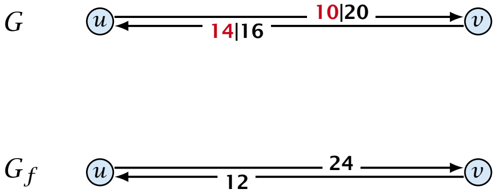

Augmenting Path Algorithm

Definition 1
An augmenting path with respect to flow f, is a path from s to t in the auxiliary graph G_f that contains only edges with non-zero capacity.

Algorithm 1 FordFulkerson($G = (V, E, c)$)

1: Initialize $f(e) \leftarrow 0$ for all edges.
2: **while** $\exists$ augmenting path p in G_f **do**
3: augment as much flow along p as possible.

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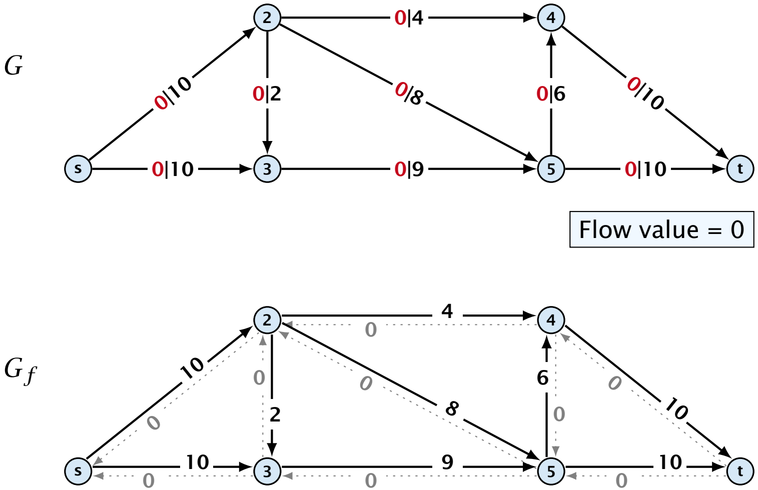

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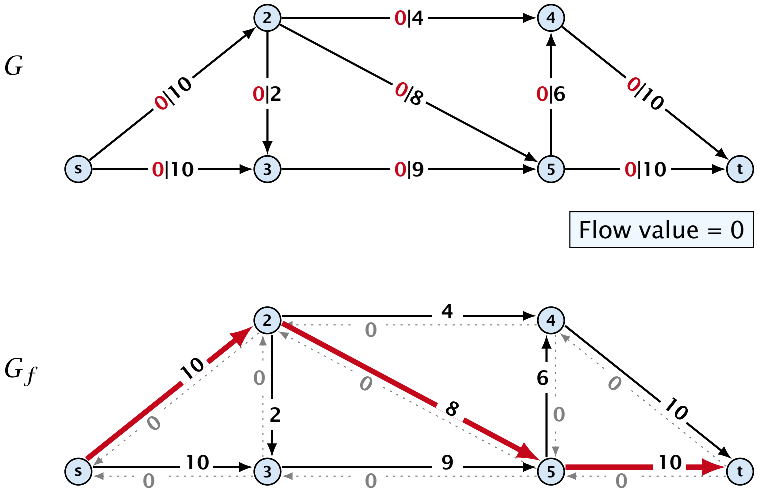

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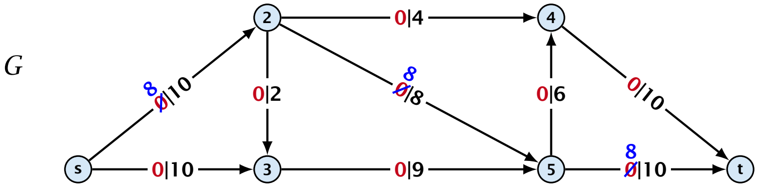
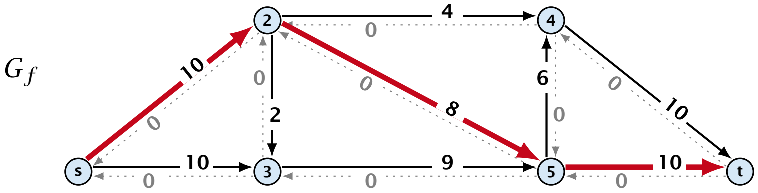


Flow value = 8



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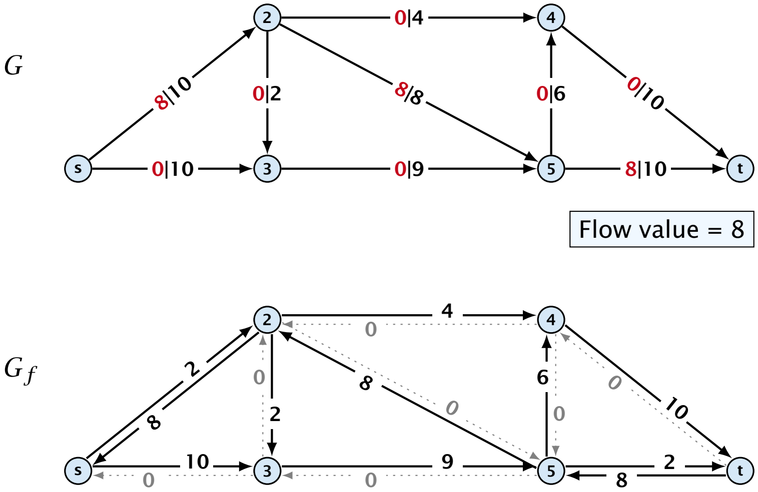

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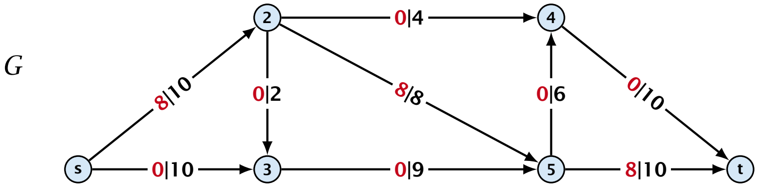

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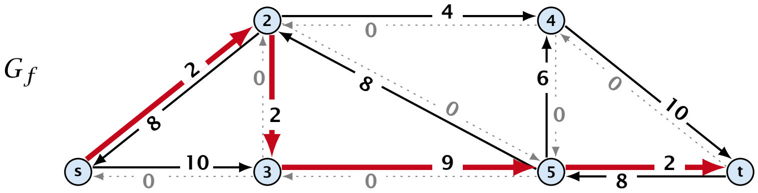

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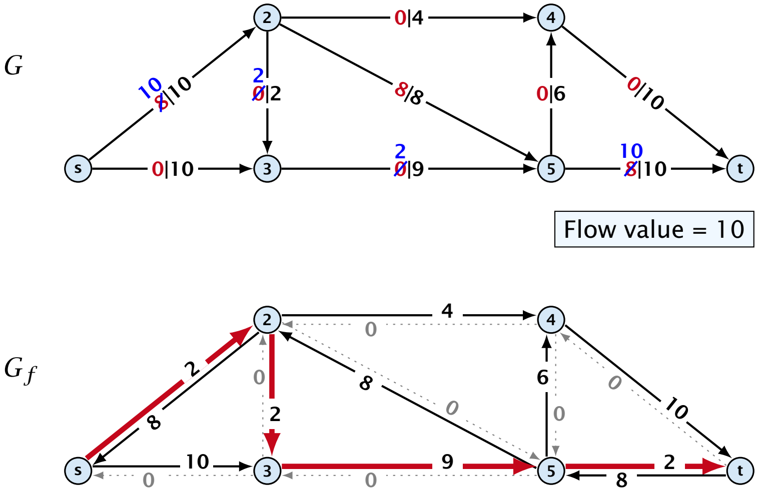

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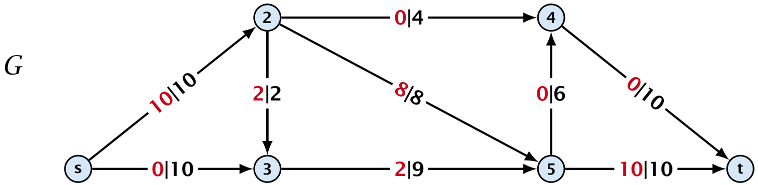

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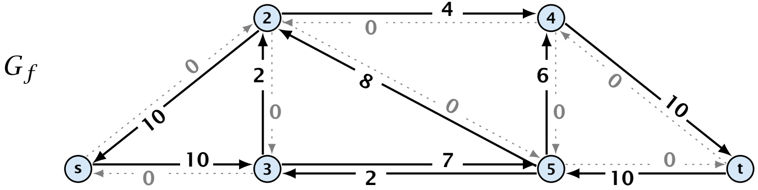
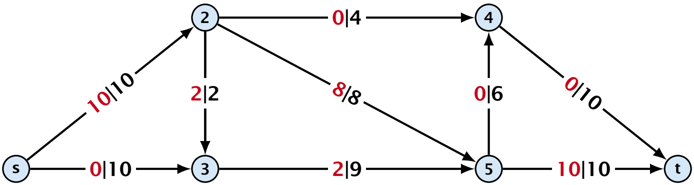


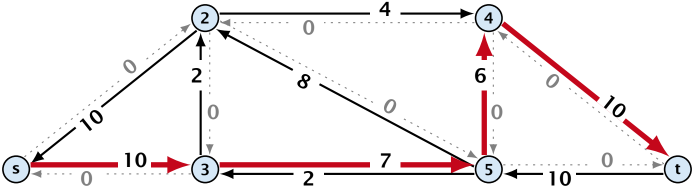
Augmenting Path Algorithm

G



Flow value = 10

G_f



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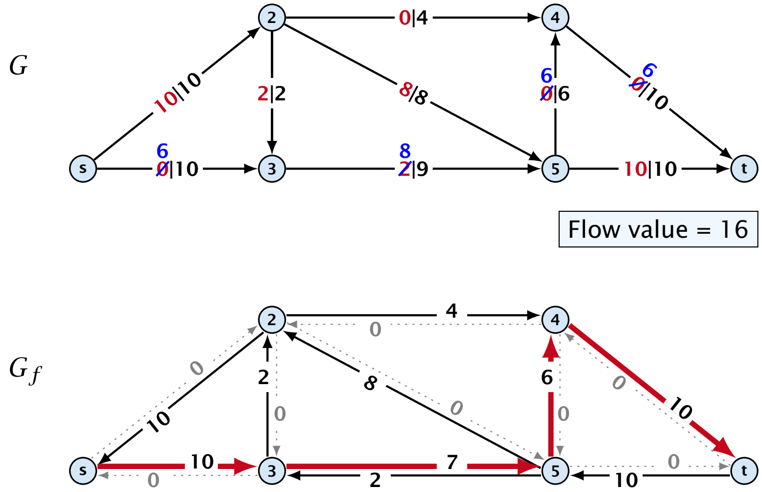

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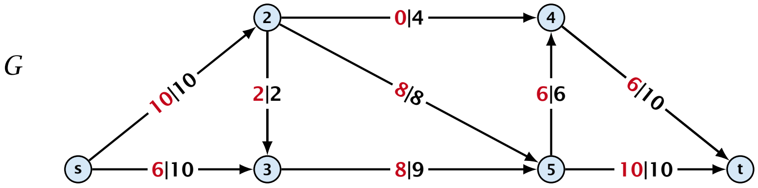

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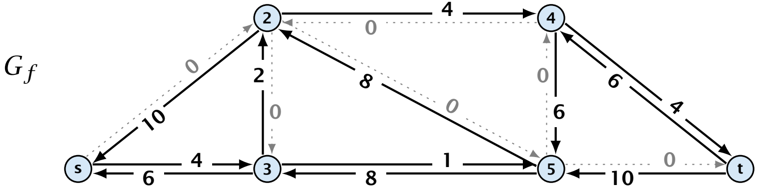

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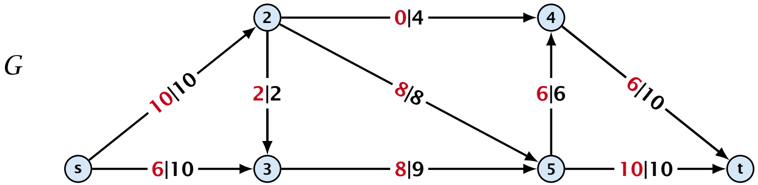

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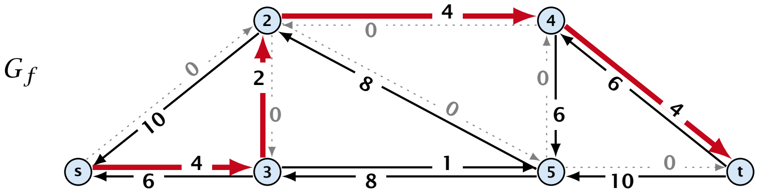

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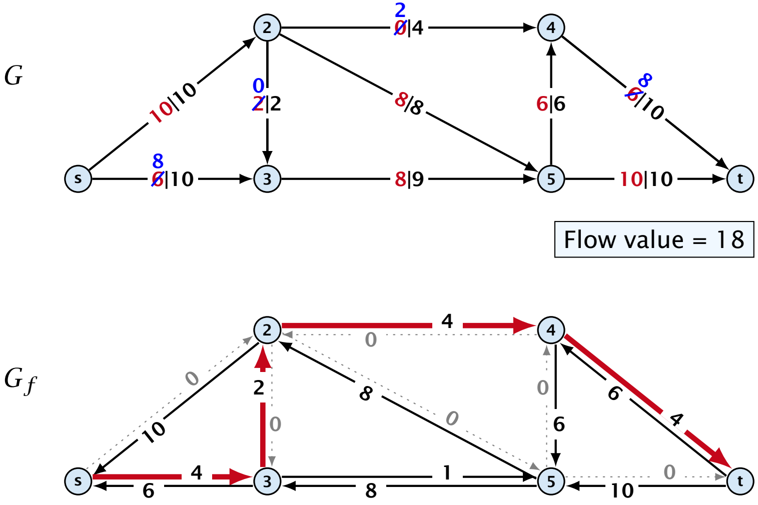

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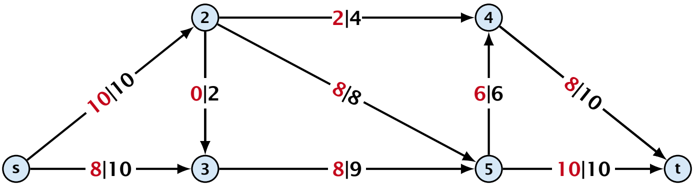

Flow value = 18

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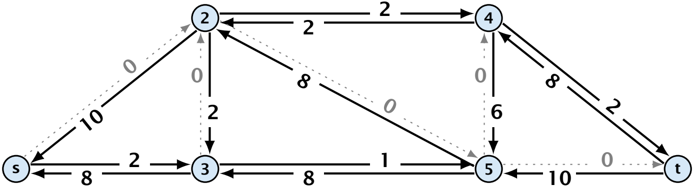

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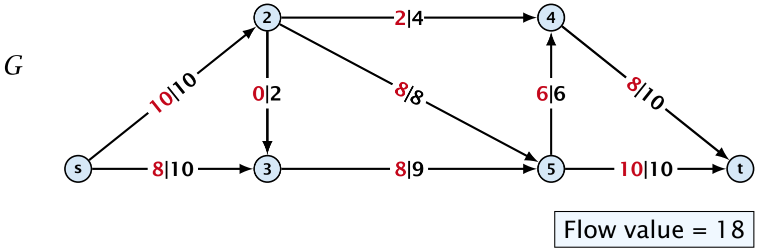

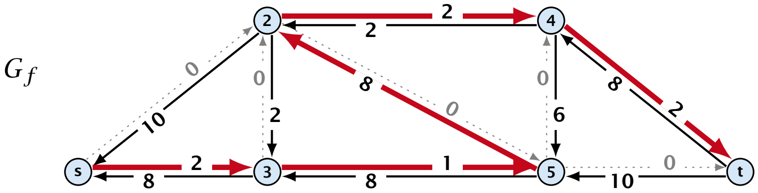

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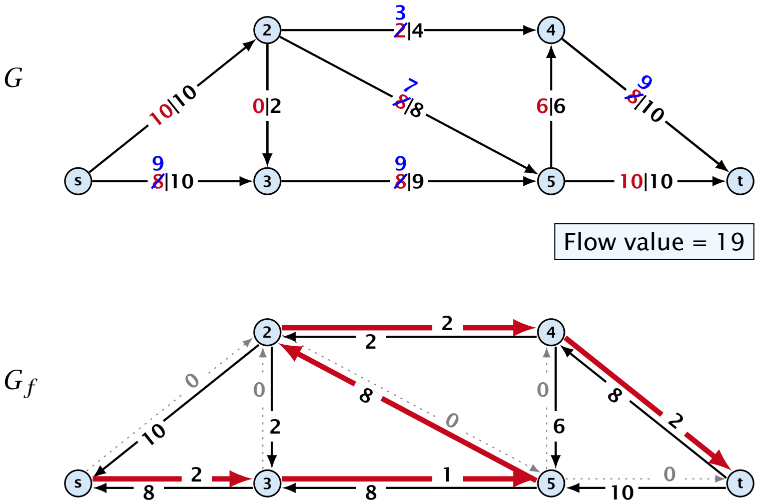

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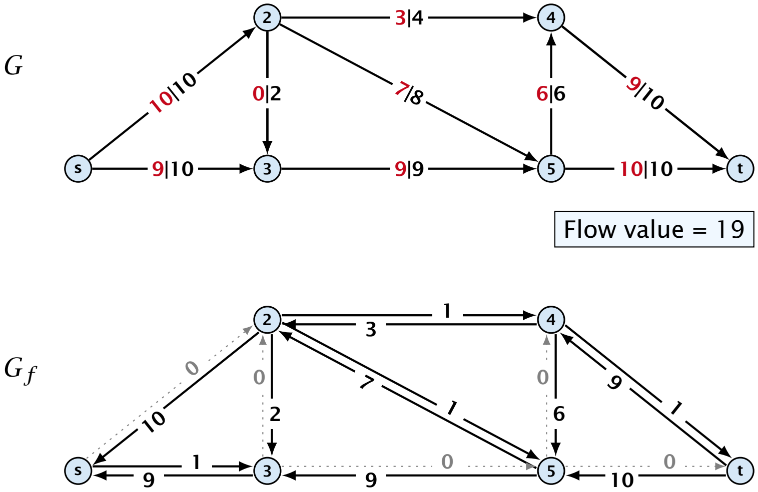

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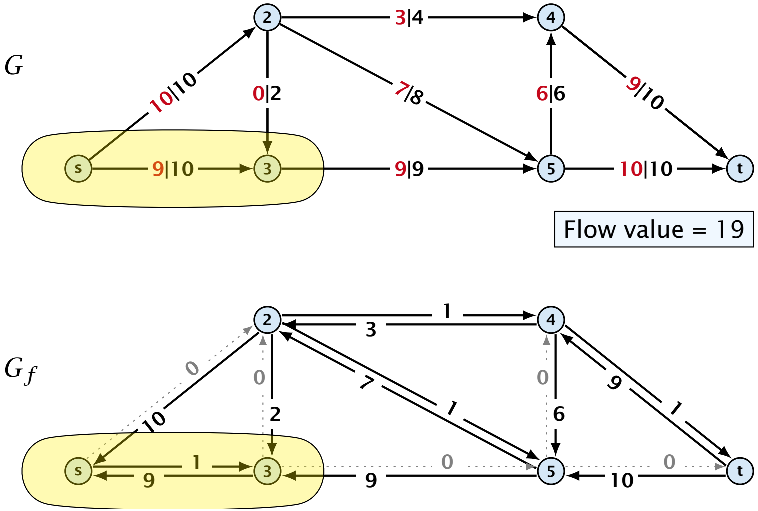

Augmenting Path Algorithm

Theorem 2

*A flow f is a maximum flow **iff** there are no augmenting paths.*

Theorem 3

The value of a maximum flow is equal to the value of a minimum cut.

Proof.

Let f be a flow. The following are equivalent:

1. There exists a cut A, B such that $\text{val}(f) = \text{cap}(A, B)$.
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2\. $\Longrightarrow$ 3.

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$\mathrm{val}(f)$

Augmenting Path Algorithm

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This finishes the proof.

Here the first equality uses the flow value lemma, and the second exploits the fact that the flow along incoming edges must be 0 as the residual graph does not have edges leaving A.

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Assumption:
All capacities are integers between 1 and C.

Invariant:
Every flow value $f(e)$ and every residual capacity $c_f(e)$ remains integral troughout the algorithm.

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The algorithm terminates in at most $\mathrm{val}(f^*) \le nC$ *iterations, where* f^* *denotes the maximum flow. Each iteration can be implemented in time* $\mathcal{O}(m)$*. This gives a total running time of* $\mathcal{O}(nmC)$*.*

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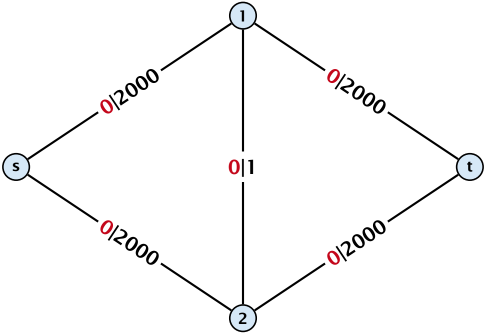
A Bad Input

Problem: The running time may not be polynomial.



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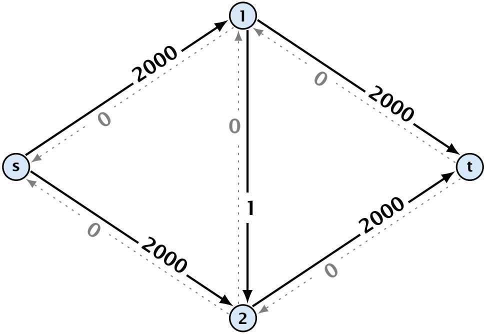

Question:

Can we tweak the algorithm so that the running time is polynomial in the input length?

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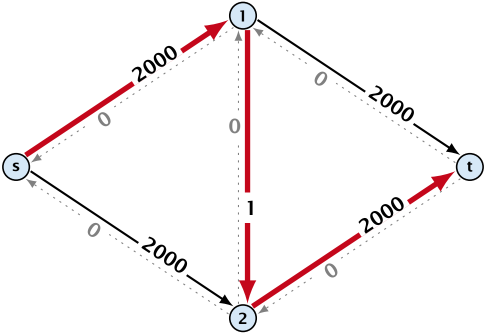

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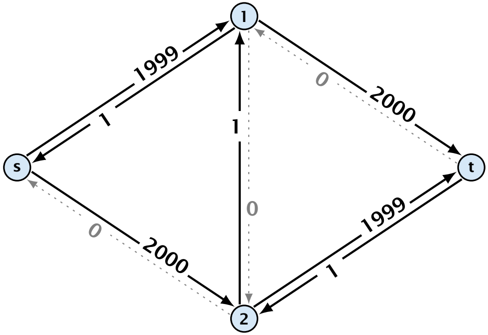

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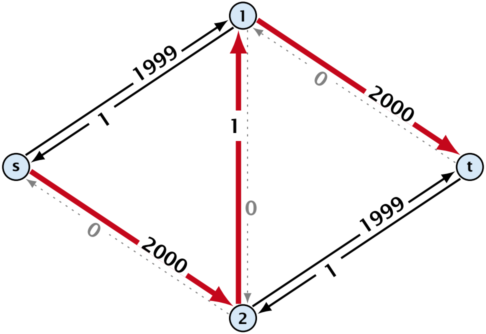

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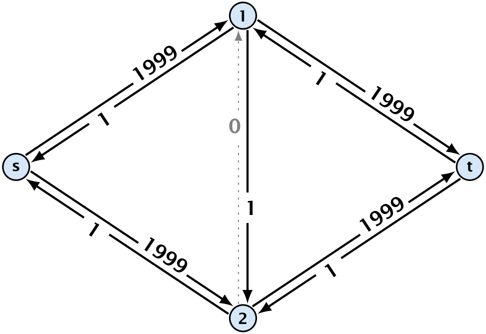

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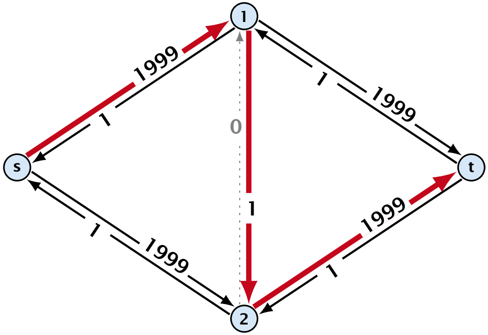

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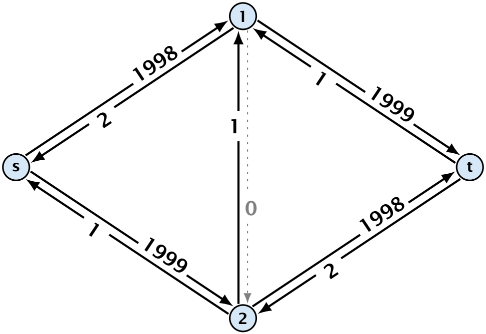

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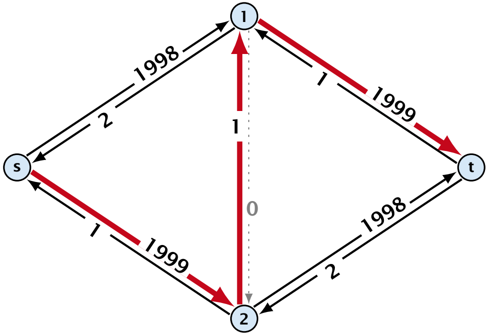

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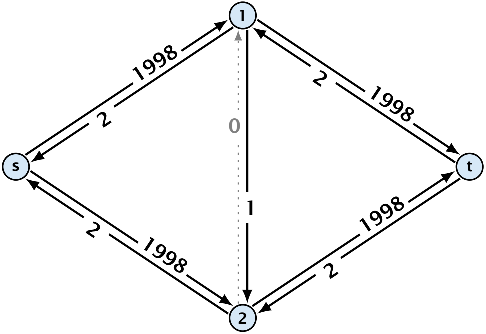

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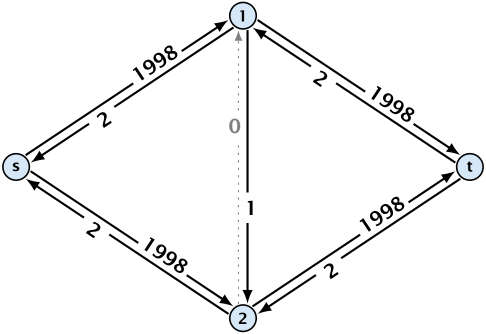

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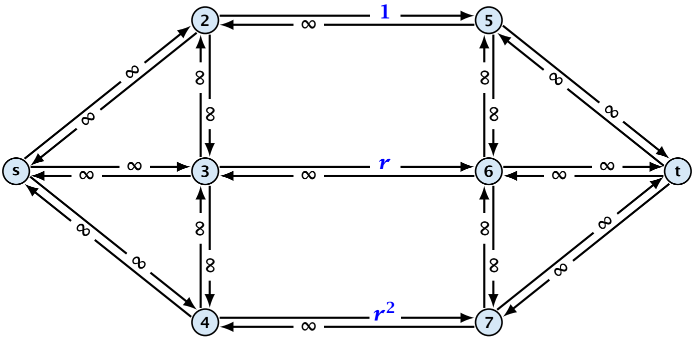
A Pathological Input

Let $r = \frac{1}{2}(\sqrt{5} - 1)$. Then $r^{n+2} = r^n - r^{n+1}$.



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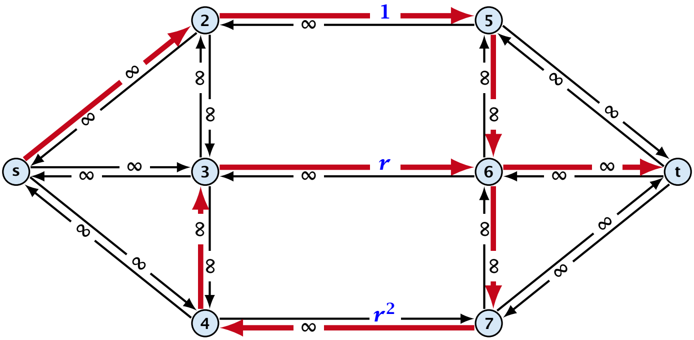

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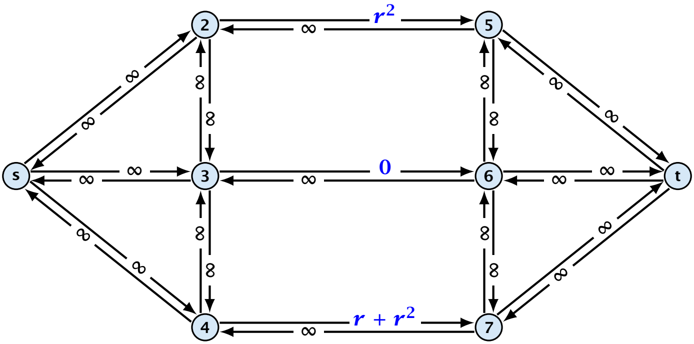

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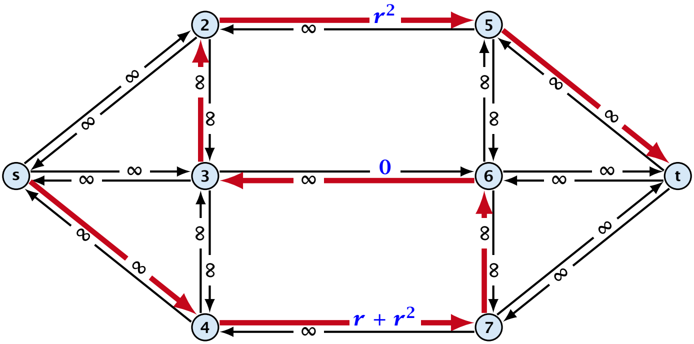

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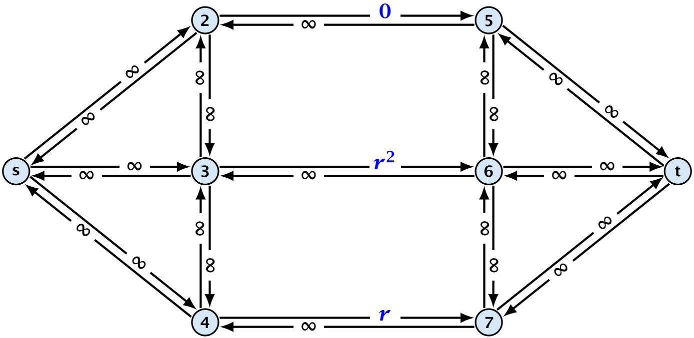

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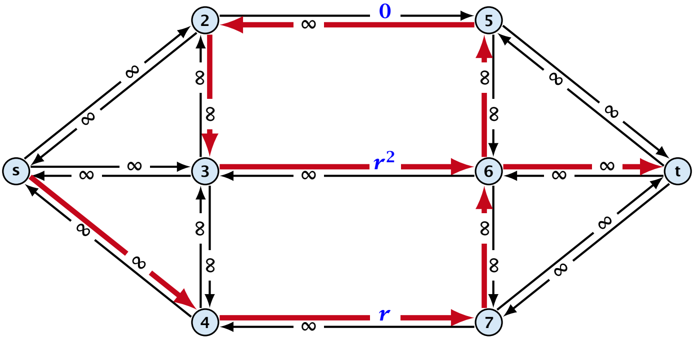

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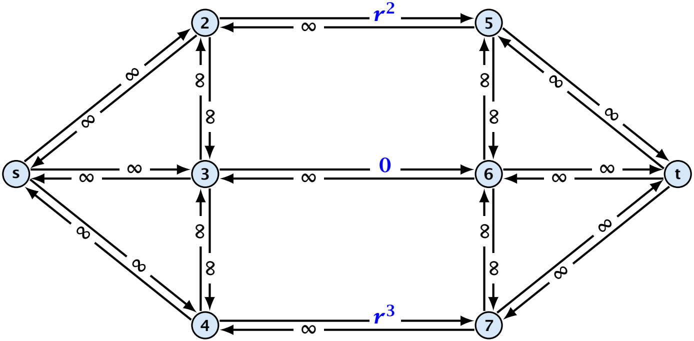

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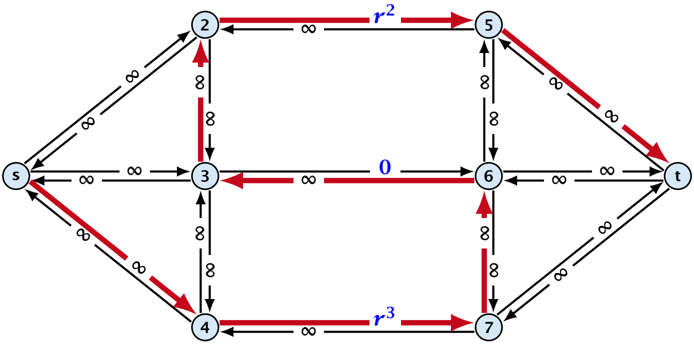

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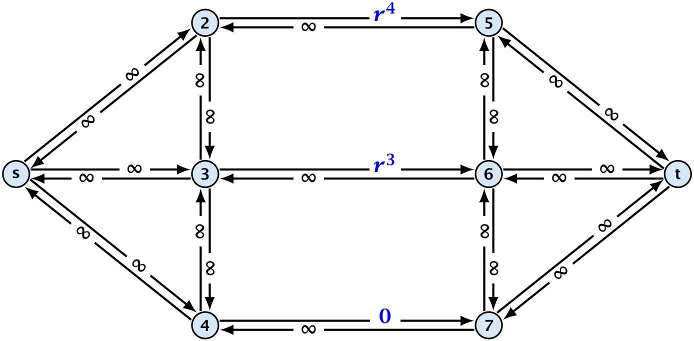

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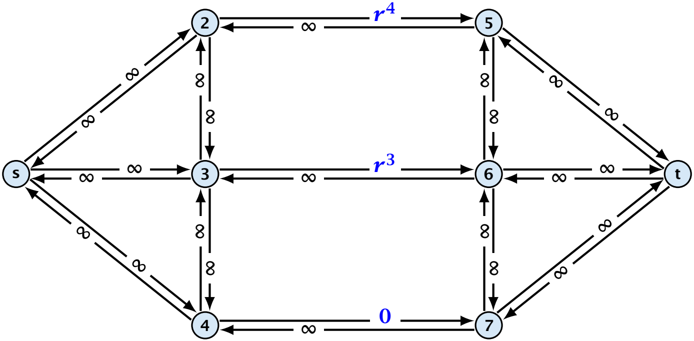

Running time may be infinite!!!

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Overview: Shortest Augmenting Paths

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The length of the shortest augmenting path never decreases.

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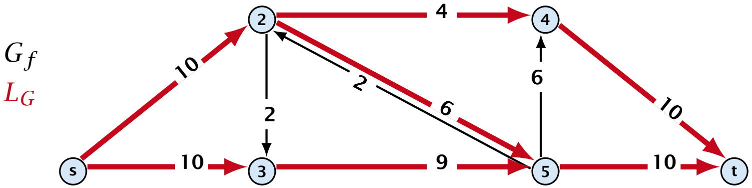

In the following we assume that the residual graph G_f does not contain zero capacity edges.

This means, we construct it in the usual sense and then delete edges of zero capacity.

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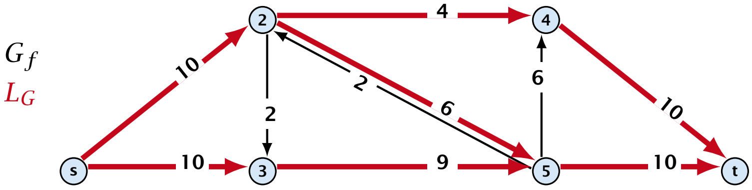

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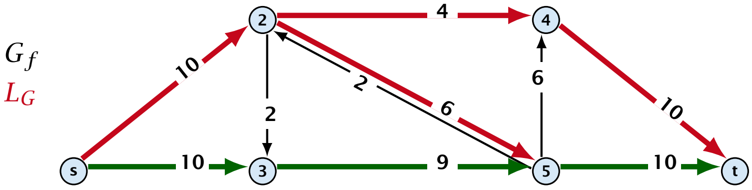

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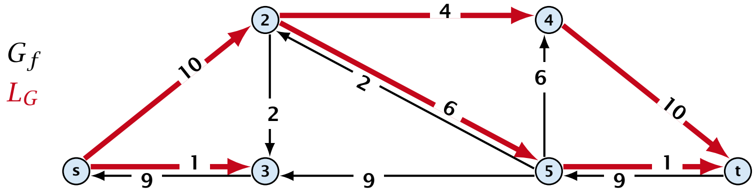

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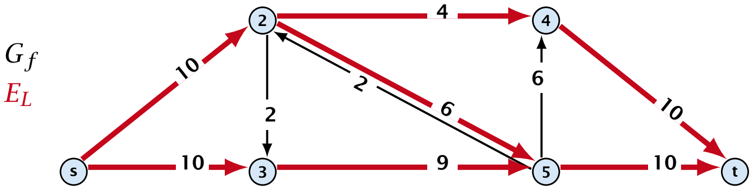

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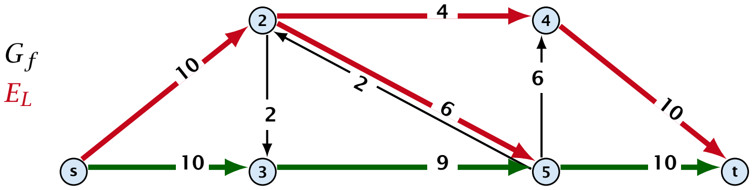

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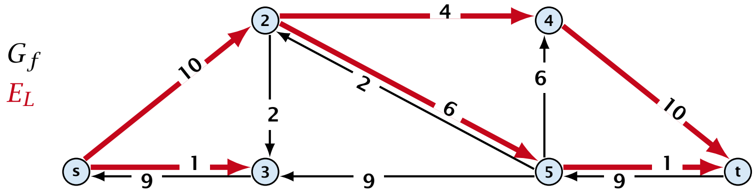

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The shortest augmenting path algorithm performs at most $\mathcal{O}(mn)$ augmentations. Each augmentation can be performed in time $\mathcal{O}(m)$.

Theorem 10 (without proof)
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The total cost for performing an augmentation during a phase is only $\mathcal{O}(n)$. For every edge in the augmenting path one has to update the residual graph G_f and has to check whether the edge is still in E_L for the next search.

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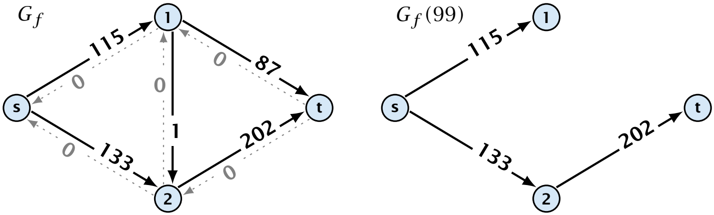

Capacity Scaling

Algorithm 2 maxflow(G, s, t, c)

foreach $e \in E$ **do** $f_e \leftarrow 0$;
$\Delta \leftarrow 2^{\lceil \log_2 C \rceil}$
while $\Delta \geq 1$ **do**
  $G_f(\Delta) \leftarrow \Delta$-residual graph
  while there is augmenting path P in $G_f(\Delta)$ **do**
    $f \leftarrow$ augment(f, c, P)
    update$(G_f(\Delta))$
  $\Delta \leftarrow \Delta/2$
return f

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- therefore after the last phase there are no augmenting paths anymore

Capacity Scaling

Assumption:
All capacities are integers between 1 and C.

Invariant:
All flows and capacities are/remain integral throughout the algorithm.

Correctness:
The algorithm computes a maxflow:

- because of integrality we have $G_f(1) = G_f$
- therefore after the last phase there are no augmenting paths anymore
- this means we have a maximum flow.

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Lemma 11

There are $\lceil \log C \rceil$ *iterations over* Δ.

Proof: obvious.

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Proof: less obvious, but simple:

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- In G_f this cut can have capacity at most $m\Delta$.
- This gives me an upper bound on the flow that I can still add.

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Theorem 14

We need $\mathcal{O}(m \log C)$ augmentations. The algorithm can be implemented in time $\mathcal{O}(m^2 \log C)$.